

3.3. Poincaré Duality: (manifolds, locally homeomorphic to \mathbb{R}^n)

Orientation Defn: A manifold of dimension n , n -manifold is a Hausdorff space M in which each point has a open nghd homeomorphic to \mathbb{R}^n . The dim of M characterized by local homology groups

$$0 \neq H_i(M, M - \{x\}; \mathbb{Z}) \approx H_i(\mathbb{R}^n, \mathbb{R}^n - \{0\}; \mathbb{Z}) \text{ by excision}$$

only for i

$$\approx \hat{H}_i(\mathbb{R}^n - \{0\}; \mathbb{Z}) \text{ since } \mathbb{R}^n \text{ is contractible}$$

$$\approx \hat{H}_i(S^{n-1}; \mathbb{Z}) \text{ since } \mathbb{R}^n - \{0\} \simeq S^{n-1}$$

Defn. A compact mnf without boundary is called "closed"
eg. S^n , $\mathbb{R}P^n$, $\mathbb{C}P^n$, $L(p, q)$, M, N closed $\Rightarrow M \times N$ closed

Poincaré' duality: • A closed, orientable, n -manifold ~~of dim n~~ M ,

there are isomorphisms $H_k(M; \mathbb{Z}) \approx H^{n-k}(M; \mathbb{Z}) \quad \forall k. (0 \leq k \leq n)$

- Without orientability we have $H_k(M; \mathbb{Z}_2) \approx H^{n-k}(M; \mathbb{Z}_2)$
- Also, since the homology groups of a closed mnf are finitely generated

$H_k(M; \mathbb{Z}) \approx H_{n-k}(M; \mathbb{Z})$ mod torsion subgroups and
torsion($H_k(M; \mathbb{Z})$) \cong ^{isom} $(H_{n-k-1}(M; \mathbb{Z}))$ for torsion subgroups.

Poincaré' duality expresses a certain symmetry in the homology of a closed orientable mnf.

eg. T^n , by induction on n it follows from Künneth formula

$$H_k(T^n; \mathbb{Z}) \approx \bigoplus_{\binom{n}{k}} \mathbb{Z} \quad \binom{n}{k} = \binom{n}{n-k}$$

$$\approx \bigoplus_{\binom{n}{n-k}} \mathbb{Z} \approx H_{n-k}(T^n; \mathbb{Z})$$

There is a nice geometric proof of Poincaré' duality by the notion of dual cell structures. Tetrahedron^{s*}, cube^{s*}, octahedron, dodecahedron & icosahedron

Given a pair of dual cell structures C & C^* on a closed surface M ; $C_0^* = C_2$, $C_1^* = C_1$, $C_2^* = C_0$. If we use \mathbb{Z} coefficients

then there is an ambiguity of sign for each cell, the choice of generator for the corresponding \mathbb{Z} summand of the cellular chain ex.

If we use \mathbb{Z}_2 -coeff then $C_i = C_{2-i}^*$ is canonical

$\partial: C_i \rightarrow C_{i-1}$ becomes $\delta: C_{2-i}^* \rightarrow C_{2-i+1}^*$
 since ∂ assigns to a cell the sum of the cells which are faces of it, while δ assigns to a cell the sum of the cells of which it is a face. Thus, $H_i(C; \mathbb{Z}_2) \cong H^{2-i}(C^*; \mathbb{Z}_2)$

For \mathbb{Z}_2 -coefficients, if M is orientable, it is possible to make consistent choices of orientations of C & C^* so that the ∂ maps agree.

For manifolds of higher dimensions the situation is analogous.

Each i -cell of C being dual to $(n-i)$ -cell of C^* which it intersects in one point "transversely"

Orientations & Homology:

What is the orientation of \mathbb{R}^n ? Preserved under rotations & reversed under reflections.

An orientation of \mathbb{R}^n at x is a choice of the generator $H_n(\mathbb{R}^n, \mathbb{R}^n - \{x\}) \cong H_{n-1}(\mathbb{R}^n - \{x\}) \cong H_{n-1}(S^{n-1})$ where S^{n-1}

rotations of S^{n-1} have degree 1, being homotopic to identity while reflections have degree -1. An orientation at y

$H_n(\mathbb{R}^n, \mathbb{R}^n - \{y\}) \cong H_n(\mathbb{R}^n, \mathbb{R}^n - B) \cong H_n(\mathbb{R}^n, \mathbb{R}^n - \{y\})$ where

where B contains x & y . This can be extended to manifolds

Def: A "local orientation" of M at a point x is a choice of a generator μ_x of the infinite cyclic group $H_n(M, M - \{x\})$.

An "orientation" of M is a function $x \rightarrow \mu_x$ assigning to each $x \in M$ a local orientation $\mu_x \in H_n(M, M - \{x\})$

satisfying local consistency condition that each $x \in M$

has a nhd $\mathbb{R}^n \subset M$ containing open ball B of finite radius about x st. all the local orientations μ_y at $y \in B$ are images

of of one generator μ_B of $H_n(M, M - B) \cong H_n(\mathbb{R}^n, \mathbb{R}^n - B)$

under the natural map $H_n(M, M - B) \cong H_n(M, M - \{y\})$

If an orientation exist then M is called orientable.

Prop: Every mfd M has an orientable two-sheeted covering space \tilde{M} .

Proof: M be an n -mfd. Let $\tilde{M} = \{ \mu_x \mid x \in M \text{ \& } \mu_x \text{ is a local orientation} \}$

$$p: \tilde{M} \rightarrow M$$

$\mu_x \mapsto x$ is a 2-1 surjection. Topologize \tilde{M} to make p

a covering map, as follows: Given $B \subset \mathbb{R}^n \subset M$ of finite radius

and a generator $\mu_B \in \text{Hk}(M, M-B)$, define $\mathcal{U}(\mu_B) = \{ \mu_x \mid x \in B \text{ \&}$

$\mu_B \mapsto \mu_x$ under $\text{Hk}(M, M-B) \rightarrow \text{Hk}(M, M-\{x\})$. Then

$\{ \mathcal{U}(\mu_B) \mid B \subset \mathbb{R}^n \subset M \}$ is a basis for the topology on \tilde{M} .

\tilde{M} is orientable, for $\mu_x \in \tilde{M}$ has a canonical orientation

$$\tilde{\mu}_x \in \text{Hk}(\tilde{M}, \tilde{M}-\mu_x) \cong \text{Hk}(\mathcal{U}(\mu_B), \mathcal{U}(\mu_B)-\mu_x) \cong \text{Hk}(B, B-\{x\})$$

$$\tilde{\mu}_x \longmapsto \mu_x$$

Prop 3.25. If M is connected, then M is orientable iff

\tilde{M} has two components. In particular, if M is simply-connected

or more generally, if $\pi_1(M)$ has no subgroup of index 2 then

M is orientable.

Proof: If M is connected, \tilde{M} has either one or two components.

If it has two components, they're each homeomorphically mapped

onto M , so M is orientable being homeomorphic to a component

of an orientable mfd. \tilde{M} . Conversely, if M is orientable it

has two orientations & each of these orientations defines a

component of \tilde{M} . The last statement: connected two-sheeted covering

spaces of M corresponds to index-two subgroup of $\pi_1(M)$.

RMK: For a commutative ring R with identity an R -orientation

on M^n is a function $M \rightarrow \coprod_{x \in M} \text{Hk}(M, M-\{x\}; R)$

If it satisfies local consistency then " R -orientable".

* Every manifold is \mathbb{Z}_2 -orientable. M is orientable $\Rightarrow M$ is R -orientable $\forall R$.

But a non-orientable manifold is \mathbb{R} -orientable iff \mathbb{R} contains a unit of order 2, which is $2=0$ in \mathbb{R} , Hence every manifold is \mathbb{Z}_2 -orientable.

Thm 3.26 Let M be a closed connected n -manifold. Then:

a) If M is \mathbb{R} -orientable, then $H_n(M; \mathbb{R}) \rightarrow H_n(M, M-\{x\}; \mathbb{R}) \cong \mathbb{R}$ is an isomorphism $\forall x \in M$.

b) If M is not \mathbb{R} -orientable, then $H_n(M; \mathbb{R}) \rightarrow H_n(M, M-\{x\}; \mathbb{R}) \cong \mathbb{R}$ is injective with image $\{r \in \mathbb{R} \mid 2r=0\} \forall x \in M$.

c) $H_i(M; \mathbb{R}) = 0$ for $i > n$.

In particular, $H_n(M; \mathbb{Z}) = \begin{cases} \mathbb{Z} & \text{if } M \text{ is orientable} \\ 0 & \text{if } M \text{ is non-orientable} \end{cases}$

$$H_n(M; \mathbb{Z}_2) = \mathbb{Z}_2$$

Defn: An element of $H_n(M; \mathbb{R})$ whose image in $H_n(M, M-\{x\}; \mathbb{R})$ is a generator for all x is called a "fundamental class" for M . (*) By Thm 3.26 a fundamental class exists if M is closed, \mathbb{R} -orientable.

Converse is also true, let $\mu \in H_n(M; \mathbb{R})$ be a fund. class & μ_x is the image in $H_n(M, M-\{x\}; \mathbb{R})$. The function $x \rightarrow \mu_x$ is then an \mathbb{R} -orientation since $H_n(M; \mathbb{R}) \rightarrow H_n(M, M-\{x\}; \mathbb{R})$ is an isomorphism. M must be compact since $H_n(M, M-B; \mathbb{R}) \cong \mathbb{R}$ for $x \in B$, $B \subset \mathbb{R}$ open.

μ_x can only be nonzero for x in the image of a cycle representing μ .

For a closed n -manifold having Δ -cx structure, consider \mathbb{Z} -coeff.

In simplicial homology a fundamental class must be represented by

some $\sum_i k_i \sigma_i$ of the n -simplices σ_i of M . Fundamental class must be mapped to a generator of $H_n(M, M-\{x\}; \mathbb{R})$ so $k_i = \pm 1$. Also

$\sum_i k_i \sigma_i$ must be a cycle. So, σ_i & σ_j must share a common $(n-1)$ -dim'd face, making $\sum_i k_i \sigma_i$ a cycle is possible iff M is orientable.

Corollary 3.28: If M is a closed connected n -manifold, the torsion subgroup of $H_{n-1}(M; \mathbb{Z})$ is trivial if M is orientable & \mathbb{Z}_2 if M is nonorientable.

Proof: Closed \Rightarrow homology groups are finitely generated

M orientable, if $H_{n-1}(M; \mathbb{Z})$ has torsion then for some prime p , $H_n(M; \mathbb{Z}_p) = H_n(M) \otimes \mathbb{Z}_p \oplus \text{Tor}(H_{n-1}(M), \mathbb{Z}_p)$

~~then~~ $H_n(M; \mathbb{Z}_p)$ would be larger than \mathbb{Z}_p coming from $H_n(M)$

M nonorientable; $H_n(M; \mathbb{Z}_m) = \begin{cases} \mathbb{Z}_2 & m \text{ even} \\ 0 & m \text{ odd} \end{cases} \rightarrow \text{Torsion subgroup } \mathbb{Z}_2$

$H_n(M; G)$ & $H_{n-1}(M; G)$ for a closed, connected n -manifold

M can be explained very nicely by cellular homology when M has a CW-structure with a single n -cell. It produces non-trivial local homology in that dimension. Consider

$$d: C_n(M) \rightarrow C_{n-1}(M) \quad C_n(M) \cong \mathbb{Z}$$

If M is orientable then d must be zero since $H_n(M) \cong \mathbb{Z}$

So $H_{n-1}(M)$ must be free. If M is non-orientable then

d takes a generator of $C_n(M)$ to twice a generator α of

a \mathbb{Z} summand of $C_{n-1}(M)$ in order for $H_n(M; \mathbb{Z}_p) = \begin{cases} \mathbb{Z}_2 & p=2 \\ 0 & \text{o/w} \end{cases}$

α must be a cycle since 2α is a boundary.

So, the torsion subgroup of $H_{n-1}(M; \mathbb{Z})$ must be \mathbb{Z}_2 generated by α

-Cap Product =

X : space, R : ring, define R -bilinear map

$$\cap: C_k(X; R) \times C^l(X; R) \rightarrow C_{k-l}(X; R) \text{ for } k \geq l \text{ by}$$

$$\sigma \cap \varphi = \varphi(\sigma|_{[v_0, \dots, v_{k-1}]}) \cdot \sigma|_{[v_k, \dots, v_k]}$$

$$\sigma: \Delta^k \rightarrow X \text{ \& } \varphi \in C^l(X; R)$$

Lemma: $\partial(\sigma \cap \varphi) = (-1)^k (\partial\sigma \cap \varphi - \sigma \cap \delta\varphi)$

Proof: $\partial(\sigma \cap \varphi) = \sum_{i=0}^k (-1)^i \varphi(\sigma|_{[v_0, \dots, \hat{v}_i, \dots, v_k]}) \sigma|_{[v_{i+1}, \dots, v_k]}$

$$+ \sum_{i=l+1}^k (-1)^i \varphi(\sigma|_{[v_0, \dots, v_{i-1}, v_{i+1}, \dots, v_k]}) \sigma|_{[v_i, \dots, \hat{v}_i, \dots, v_k]}$$

$$\sigma \cap \delta\varphi = \sum_{i=0}^{d+1} (-1)^i \varphi(\sigma|_{[v_0, \dots, \hat{v}_i, \dots, v_{d+1}]}) \sigma|_{[v_{i+1}, \dots, v_k]}$$

$$\partial(\sigma \cap \varphi) = \sum_{i=l}^k (-1)^{i-l} \varphi(\sigma|_{[v_0, \dots, v_k]}) \sigma|_{[v_i, \dots, \hat{v}_i, \dots, v_k]}$$

$$\begin{aligned} \partial(\sigma \cap \varphi) - \sigma \cap \delta\varphi &= -(-1)^{d+l} \varphi(\sigma|_{[v_0, \dots, v_k]}) \sigma|_{[v_{d+l+1}, \dots, v_k]} \\ &\quad + \sum_{i=l+1}^k (-1)^i \varphi(\sigma|_{[v_0, \dots, v_k]}) \sigma|_{[v_i, \dots, \hat{v}_i, \dots, v_k]} \\ &= \sum_{i=l}^k (-1)^i \varphi(\sigma|_{[v_0, \dots, v_k]}) \sigma|_{[v_i, \dots, \hat{v}_i, \dots, v_k]} = (-1)^l \sum_{i=l}^k (-1)^{i-l} \varphi(\sigma|_{[v_0, \dots, v_k]}) \sigma|_{[v_i, \dots, \hat{v}_i, \dots, v_k]} \\ &= \pm \partial(\sigma \cap \varphi) \end{aligned}$$

is well-defined

$\partial(\sigma \cap \varphi) = \pm (\partial\sigma \cap \varphi - \sigma \cap \delta\varphi)$ so cap product of a cycle & a cocycle is a cycle.

If $\partial\sigma = 0$ then $\partial(\sigma \cap \varphi) = \pm (\sigma \cap \delta\varphi)$ so cap product of a cycle & coboundary is a boundary.

If $\delta\varphi = 0$ then $\partial(\sigma \cap \varphi) = \pm (\partial\sigma \cap \varphi)$, so cap product of a boundary and a cocycle is a boundary.

So, this induces a map (well-defined)

$$\cap: H_k(X; \mathbb{R}) \times H^l(X; \mathbb{R}) \xrightarrow{\cap} H_{k-l}(X; \mathbb{R})$$

$$([\sigma], [\varphi]) \longmapsto [\sigma \cap \varphi]$$

Lemma: Cap product satisfies naturality. Given a map

$f: X \rightarrow Y$ then

$$\begin{array}{ccc} H_k(X) \times H^l(X) & \xrightarrow{\cap} & H_{k-l}(X) \\ \downarrow f_* & \uparrow f^* & \downarrow f_* \\ H_k(Y) \times H^l(Y) & \xrightarrow{\cap} & H_{k-l}(Y) \end{array}$$

$$f_*(\alpha \cap f^*\beta) = f_*\alpha \cap \beta$$

Proof:

$$\begin{array}{ccc} C_k(X) \times C^l(X) & \longrightarrow & C_{k-l}(X) \\ \downarrow f_\# & \uparrow f^\# & \downarrow f_\# \\ C_k(Y) \times C^l(Y) & \longrightarrow & C_{k-l}(Y) \end{array}$$

$$\sigma \cap (f^\# \varphi) = (f^\# \varphi)(\sigma|_{[v_0, v_2]}) \cdot \sigma|_{[v_2, v_1]} \\ = \varphi(f\sigma|_{[v_0, v_2]}) \cdot \sigma|_{[v_2, v_1]}$$

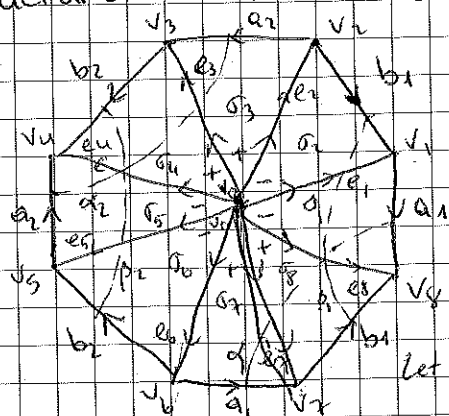
$$f_\#(\sigma \cap f^\# \varphi) = \varphi(f\sigma|_{[v_0, v_2]}) \cdot f\sigma|_{[v_2, v_1]} = (f\sigma) \cap \varphi \\ = f_\#(\sigma) \cap \varphi \quad \square$$

Thm 3.30 (Poincaré Duality): If M is a closed \mathbb{R} -orientable n -manifold with fundamental class $[M] \in H_n(M; \mathbb{R})$, then the map

$$D: H^k(M; \mathbb{R}) \rightarrow H_{n-k}(M; \mathbb{R}) \text{ given by}$$

$$\alpha \longmapsto [M] \cap \alpha \text{ is an isomorphism } \square$$

Exp: 3.31 Surfaces: Let M be a closed orientable surface of genus g , obtained as usual from a $4g$ -gon by identifying pairs of edges according to the word $a_1 b_1 a_1^{-1} b_1^{-1} \dots a_g b_g a_g^{-1} b_g^{-1}$. A Δ -complex structure on M is obtained by cutting off the $4g$ -gon to its center.



A fundamental class $[M]$:

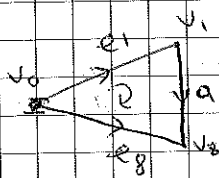
$$-\sigma_1 - \sigma_2 + \sigma_3 + \sigma_4 + \sigma_5 - \sigma_6 + \sigma_7 + \sigma_8$$

Under the isomorphism $H^1(M) \cong \text{Hom}(H_1(M), \mathbb{R})$

$$\alpha_i = a_i^\# \quad \beta_i = b_i^\#$$

Let $\alpha_i = [\varphi_i] \quad \beta_i = [\psi_i]$ for cocycles φ_i & ψ_i

$$[M] \cap \varphi_1 = (-\sigma_1 - \sigma_2 + \sigma_3 + \sigma_4 - \sigma_5 - \sigma_6 + \sigma_7 + \sigma_8) \cap \varphi_1 \\ = -\underbrace{\sigma_1 \cap \varphi_1}_0 - \underbrace{\sigma_2 \cap \varphi_1}_0 + \underbrace{\sigma_3 \cap \varphi_1}_0 + \underbrace{\sigma_4 \cap \varphi_1}_0 - \underbrace{\sigma_5 \cap \varphi_1}_0 - \underbrace{\sigma_6 \cap \varphi_1}_0 + \underbrace{\sigma_7 \cap \varphi_1}_0 + \underbrace{\sigma_8 \cap \varphi_1}_0$$



$$\sigma_1 \cap \varphi_1 = \varphi_1(\sigma_1|_{[v_0, v_1]}) \cdot \sigma_1|_{[v_1, v_2]} = 0, \quad \sigma_1|_{[v_1, v_2]} = 0$$

$$\sigma_7 \cap \varphi_1 = \varphi_1(\sigma_7|_{[v_0, v_1]}) \cdot \sigma_7|_{[v_1, v_2]} = 0, \quad \sigma_7|_{[v_0, v_1]} = 0$$

$$\sigma_8 \cap \varphi_1 = \varphi_1(\sigma_8|_{[v_0, v_1]}) \cdot \sigma_8|_{[v_1, v_2]} = 1 \cdot \sigma_8|_{[v_1, v_2]} = b_1$$

Similarly $[M] \cap \varphi_2 = b_2$

$$[M] \cap \psi_1 = -a_1 \quad [M] \cap \psi_2 = -a_2$$

$$\text{Thus } \begin{array}{ccc} H^1(M) & \longrightarrow & H_1(M) \\ \alpha_i & \longmapsto & [b_i] \\ \beta_i & \longmapsto & -[a_i] \end{array}$$